

NAG C Library Function Document

nag_zsprfs (f07qvc)

1 Purpose

nag_zsprfs (f07qvc) returns error bounds for the solution of a complex symmetric system of linear equations with multiple right-hand sides, $AX = B$ using packed storage. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Specification

```
void nag_zsprfs (Nag_OrderType order, Nag_UploType uplo, Integer n, Integer nrhs,
  const Complex ap[], const Complex afp[], const Integer ipiv[],
  const Complex b[], Integer pdb, Complex x[], Integer pdx, double ferr[],
  double berr[], NagError *fail)
```

3 Description

nag_zsprfs (f07qvc) returns the backward errors and estimated bounds on the forward errors for the solution of a complex symmetric system of linear equations with multiple right-hand sides $AX = B$, using packed storage. The function handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of nag_zsprfs (f07qvc) in terms of a single right-hand side b and solution x .

Given a computed solution x , the function computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b \\ |\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.$$

Then the function estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where \hat{x} is the true solution.

For details of the method the f07 Chapter Introduction.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

1: **order** – Nag_OrderType

Input

On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order = Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

Constraint: **order = Nag_RowMajor** or **Nag_ColMajor**.

- 2: **uplo** – Nag_UploType *Input*
On entry: indicates whether the upper or lower triangular part of A is stored and how A is to be factorized, as follows:
 if **uplo** = **Nag_Upper**, the upper triangular part of A is stored and A is factorized as $PUDU^T P^T$, where U is upper triangular;
 if **uplo** = **Nag_Lower**, the lower triangular part of A is stored and A is factorized as $PLDL^T P^T$, where L is lower triangular.
Constraint: **uplo** = **Nag_Upper** or **Nag_Lower**.
- 3: **n** – Integer *Input*
On entry: n , the order of the matrix A .
Constraint: $n \geq 0$.
- 4: **nrhs** – Integer *Input*
On entry: r , the number of right-hand sides.
Constraint: **nrhs** ≥ 0 .
- 5: **ap**[dim] – const Complex *Input*
Note: the dimension, dim , of the array **ap** must be at least $\max(1, n \times (n + 1)/2)$.
On entry: the n by n original symmetric matrix A as supplied to nag_zsptf (f07qvc).
- 6: **afp**[dim] – const Complex *Input*
Note: the dimension, dim , of the array **afp** must be at least $\max(1, n \times (n + 1)/2)$.
On entry: details of the factorization of A stored in packed form, as returned by nag_zsptf (f07qvc).
- 7: **ipiv**[dim] – const Integer *Input*
Note: the dimension, dim , of the array **ipiv** must be at least $\max(1, n)$.
On entry: details of the interchanges and the block structure of D , as returned by nag_zsptf (f07qvc).
- 8: **b**[dim] – const Complex *Input*
Note: the dimension, dim , of the array **b** must be at least $\max(1, pdb \times nrhs)$ when **order** = **Nag_ColMajor** and at least $\max(1, pdb \times n)$ when **order** = **Nag_RowMajor**.
 If **order** = **Nag_ColMajor**, the (i, j) th element of the matrix B is stored in $b[(j - 1) \times pdb + i - 1]$ and if **order** = **Nag_RowMajor**, the (i, j) th element of the matrix B is stored in $b[(i - 1) \times pdb + j - 1]$.
On entry: the n by r right-hand side matrix B .
- 9: **pdb** – Integer *Input*
On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **b**.
Constraints:
 if **order** = **Nag_ColMajor**, **pdb** $\geq \max(1, n)$;
 if **order** = **Nag_RowMajor**, **pdb** $\geq \max(1, nrhs)$.
- 10: **x**[dim] – Complex *Input/Output*
Note: the dimension, dim , of the array **x** must be at least $\max(1, pdx \times nrhs)$ when **order** = **Nag_ColMajor** and at least $\max(1, pdx \times n)$ when **order** = **Nag_RowMajor**.

If **order** = **Nag_ColMajor**, the (i, j) th element of the matrix X is stored in $\mathbf{x}[(j - 1) \times \mathbf{pdx} + i - 1]$ and if **order** = **Nag_RowMajor**, the (i, j) th element of the matrix X is stored in $\mathbf{x}[(i - 1) \times \mathbf{pdx} + j - 1]$.

On entry: the n by r solution matrix X , as returned by nag_zsprs (f07qsc).

On exit: the improved solution matrix X .

11: **pdx** – Integer *Input*

On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array \mathbf{x} .

Constraints:

if **order** = **Nag_ColMajor**, **pdx** \geq $\max(1, \mathbf{n})$;
if **order** = **Nag_RowMajor**, **pdx** \geq $\max(1, \mathbf{nrhs})$.

12: **ferr**[*dim*] – double *Output*

Note: the dimension, *dim*, of the array **ferr** must be at least $\max(1, \mathbf{nrhs})$.

On exit: **ferr**[$j - 1$] contains an estimated error bound for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.

13: **berr**[*dim*] – double *Output*

Note: the dimension, *dim*, of the array **berr** must be at least $\max(1, \mathbf{nrhs})$.

On exit: **berr**[$j - 1$] contains the component-wise backward error bound β for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.

14: **fail** – NagError * *Output*

The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, **n** = $\langle value \rangle$.

Constraint: **n** \geq 0.

On entry, **nrhs** = $\langle value \rangle$.

Constraint: **nrhs** \geq 0.

On entry, **pdb** = $\langle value \rangle$.

Constraint: **pdb** $>$ 0.

On entry, **pdx** = $\langle value \rangle$.

Constraint: **pdx** $>$ 0.

NE_INT_2

On entry, **pdb** = $\langle value \rangle$, **n** = $\langle value \rangle$.

Constraint: **pdb** \geq $\max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$, **nrhs** = $\langle value \rangle$.

Constraint: **pdb** \geq $\max(1, \mathbf{nrhs})$.

On entry, **pdx** = $\langle value \rangle$, **n** = $\langle value \rangle$.

Constraint: **pdx** \geq $\max(1, \mathbf{n})$.

On entry, **pdx** = $\langle value \rangle$, **nrhs** = $\langle value \rangle$.

Constraint: **pdx** \geq $\max(1, \mathbf{nrhs})$.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter $\langle value \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

The bounds returned in **ferr** are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of $16n^2$ real floating-point operations. Each step of iterative refinement involves an additional $24n^2$ real operations. At most 5 steps of iterative refinement are performed, but usually only 1 or 2 steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form $Ax = b$; the number is usually 5 and never more than 11. Each solution involves approximately $8n^2$ real operations.

The real analogue of this function is nag_dsprfs (f07phc).

9 Example

To solve the system of equations $AX = B$ using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} -0.39 - 0.71i & 5.14 - 0.64i & -7.86 - 2.96i & 3.80 + 0.92i \\ 5.14 - 0.64i & 8.86 + 1.81i & -3.52 + 0.58i & 5.32 - 1.59i \\ -7.86 - 2.96i & -3.52 + 0.58i & -2.83 - 0.03i & -1.54 - 2.86i \\ 3.80 + 0.92i & 5.32 - 1.59i & -1.54 - 2.86i & -0.56 + 0.12i \end{pmatrix}$$

and

$$B = \begin{pmatrix} -55.64 + 41.22i & -19.09 - 35.97i \\ -48.18 + 66.00i & -12.08 - 27.02i \\ -0.49 - 1.47i & 6.95 + 20.49i \\ -6.43 + 19.24i & -4.59 - 35.53i \end{pmatrix}.$$

Here A is symmetric, stored in packed form, and must first be factorized by nag_zsprtf (f07qrc).

9.1 Program Text

```

/* nag_zsprfs (f07qvc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagx04.h>

```

```

int main(void)
{
    /* Scalars */
    Integer i, j, n, nrhs, ap_len, AFP_len;
    Integer berr_len, ferr_len, pdb, pdx;
    Integer exit_status=0;
    NagError fail;
    Nag_UploType uplo_enum;
    Nag_OrderType order;
    /* Arrays */
    Integer *ipiv=0;
    char uplo[2];
    Complex *AFP=0, *ap=0, *b=0, *x=0;
    double *berr=0, *ferr=0;

#ifdef NAG_COLUMN_MAJOR
#define A_UPPER(I,J) ap[J*(J-1)/2 + I - 1]
#define A_LOWER(I,J) ap[(2*n-J)*(J-1)/2 + I - 1]
#define B(I,J) b[(J-1)*pdb + I - 1]
#define X(I,J) x[(J-1)*pdx + I - 1]
    order = Nag_ColMajor;
#else
#define A_LOWER(I,J) ap[I*(I-1)/2 + J - 1]
#define A_UPPER(I,J) ap[(2*n-I)*(I-1)/2 + J - 1]
#define B(I,J) b[(I-1)*pdb + J - 1]
#define X(I,J) x[(I-1)*pdx + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
    Vprintf("f07qvc Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[\n] ");
    Vscanf("%ld%ld%*[\n] ", &n, &nrhs);
    ap_len = n * (n + 1)/2;
    AFP_len = n * (n + 1)/2;
    berr_len = nrhs;
    ferr_len = nrhs;
#ifdef NAG_COLUMN_MAJOR
    pdb = n;
    pdx = n;
#else
    pdb = nrhs;
    pdx = nrhs;
#endif

    /* Allocate memory */
    if ( !(ipiv = NAG_ALLOC(n, Integer)) ||
        !(AFP = NAG_ALLOC(AFP_len, Complex)) ||
        !(ap = NAG_ALLOC(ap_len, Complex)) ||
        !(b = NAG_ALLOC(n * nrhs, Complex)) ||
        !(x = NAG_ALLOC(n * nrhs, Complex)) ||
        !(berr = NAG_ALLOC(berr_len, double)) ||
        !(ferr = NAG_ALLOC(ferr_len, double)) )
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read A and B from data file, and copy A to AFP and B to X */
    Vscanf(" ' %1s '%*[\n] ", uplo);
    if (*(unsigned char *)uplo == 'L')
        uplo_enum = Nag_Lower;
    else if (*(unsigned char *)uplo == 'U')
        uplo_enum = Nag_Upper;
    else
    {
        Vprintf("Unrecognised character for Nag_UploType type\n");
        exit_status = -1;
        goto END;
    }
}

```

```

    }
    if (uplo_enum == Nag_Upper)
    {
        for (i = 1; i <= n; ++i)
        {
            for (j = i; j <= n; ++j)
                Vscanf(" ( %lf , %lf )", &A_UPPER(i,j).re, &A_UPPER(i,j).im);
        }
        Vscanf("%*[\n] ");
    }
    else
    {
        for (i = 1; i <= n; ++i)
        {
            for (j = 1; j <= i; ++j)
                Vscanf(" ( %lf , %lf )", &A_LOWER(i,j).re, &A_LOWER(i,j).im);
        }
        Vscanf("%*[\n] ");
    }
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= nrhs; ++j)
            Vscanf(" ( %lf , %lf )", &B(i,j).re, &B(i,j).im);
    }
    Vscanf("%*[\n] ");

    for (i = 1; i <= n * (n + 1) / 2; ++i)
    {
        afp[i-1].re = ap[i-1].re;
        afp[i-1].im = ap[i-1].im;
    }
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= nrhs; ++j)
        {
            X(i,j).re = B(i,j).re;
            X(i,j).im = B(i,j).im;
        }
    }
    /* Factorize A in the array AFP */
    f07qrc(order, uplo_enum, n, afp, ipiv, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from f07qrc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    /* Compute solution in the array X */
    f07qsc(order, uplo_enum, n, nrhs, afp, ipiv, x, pdx, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from f07qsc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    /* Improve solution, and compute backward errors and */
    /* estimated bounds on the forward errors */
    f07qvc(order, uplo_enum, n, nrhs, ap, afp, ipiv, b, pdb,
           x, pdx, ferr, berr, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from f07qvc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    /* Print solution */
    x04dbc(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs, x, pdx,
           Nag_BracketForm, "%7.4f", "Solution(s)", Nag_IntegerLabels,
           0, Nag_IntegerLabels, 0, 80, 0, 0, &fail);
    if (fail.code != NE_NOERROR)
    {

```

```

    Vprintf("Error from x04dbc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
Vprintf("\nBackward errors (machine-dependent)\n");
for (j = 1; j <= nrhs; ++j)
    Vprintf("%11.1e%s", berr[j-1], j%4==0 ? "\n": " ");
Vprintf("\nEstimated forward error bounds (machine-dependent)\n");
for (j = 1; j <= nrhs; ++j)
    Vprintf("%11.1e%s", ferr[j-1], j%4==0 ? "\n": " ");
Vprintf("\n");
END:
if (ipiv) NAG_FREE(ipiv);
if (afp) NAG_FREE(afp);
if (ap) NAG_FREE(ap);
if (b) NAG_FREE(b);
if (x) NAG_FREE(x);
if (berr) NAG_FREE(berr);
if (ferr) NAG_FREE(ferr);
return exit_status;
}

```

9.2 Program Data

f07qvc Example Program Data

```

  4  2                                     :Values of N and NRHS
  'L'                                     :Value of UPLO
(-0.39,-0.71)
( 5.14,-0.64) ( 8.86, 1.81)
(-7.86,-2.96) (-3.52, 0.58) (-2.83,-0.03)
( 3.80, 0.92) ( 5.32,-1.59) (-1.54,-2.86) (-0.56, 0.12) :End of matrix A
(-55.64, 41.22) (-19.09,-35.97)
(-48.18, 66.00) (-12.08,-27.02)
( -0.49, -1.47) ( 6.95, 20.49)
( -6.43, 19.24) ( -4.59,-35.53)                                     :End of matrix B

```

9.3 Program Results

f07qvc Example Program Results

```

Solution(s)
           1           2
1 ( 1.0000,-1.0000) (-2.0000,-1.0000)
2 (-2.0000, 5.0000) ( 1.0000,-3.0000)
3 ( 3.0000,-2.0000) ( 3.0000, 2.0000)
4 (-4.0000, 3.0000) (-1.0000, 1.0000)

Backward errors (machine-dependent)
 1.0e-16    6.7e-17
Estimated forward error bounds (machine-dependent)
 1.2e-14    1.2e-14

```
